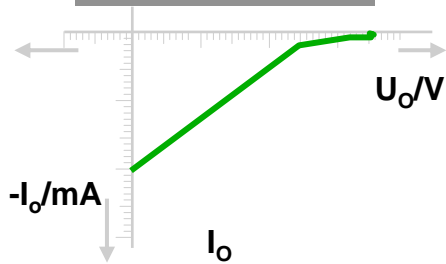




Beobachtung der Verbindung SK₁ und SK₂

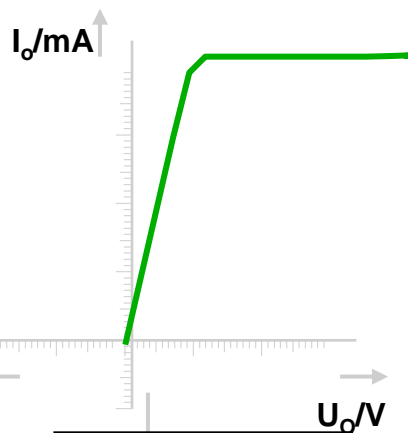
Digitale Systeme

Ausgangskennlinie bei „H“ am Ausgang



Beobachtungspunkt

I₁

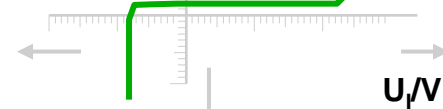


Ausgangskennlinie bei „L“ am Ausgang

U_o/V

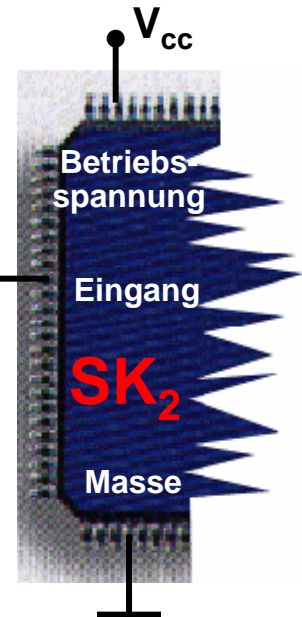
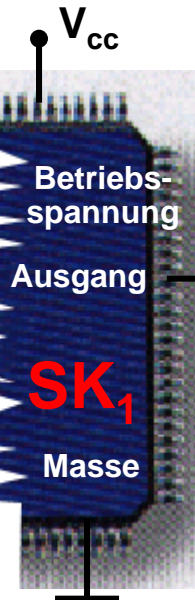
U_o=U₁

I₁/mA



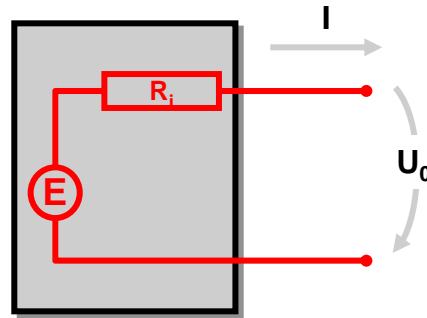
Eingangskennlinie

U₁/V

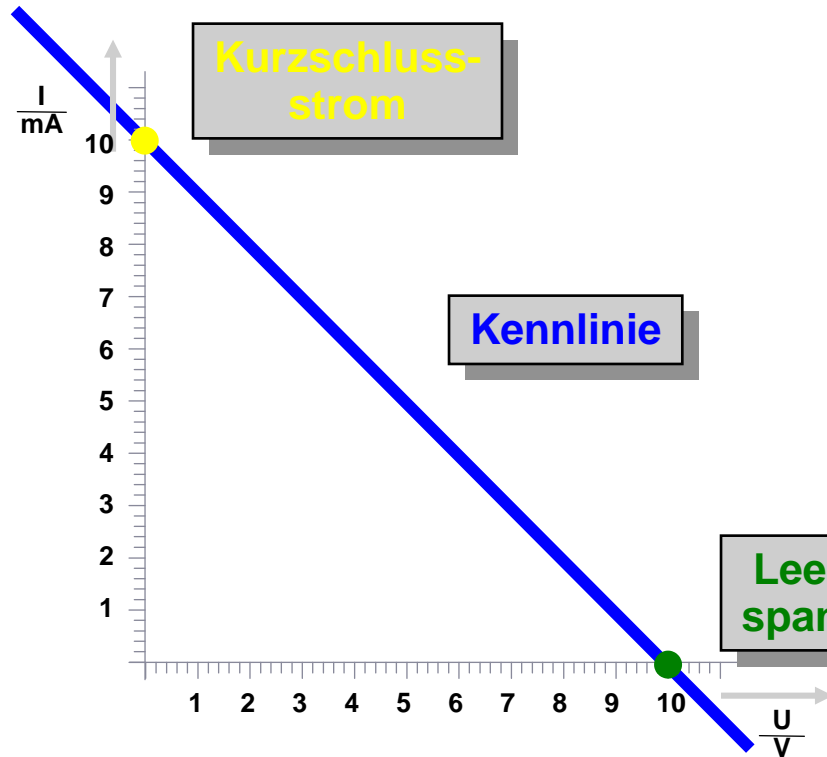
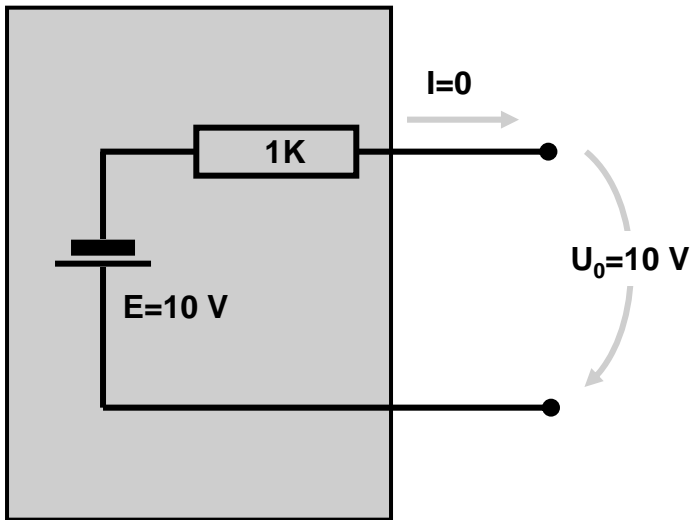




Zweipol

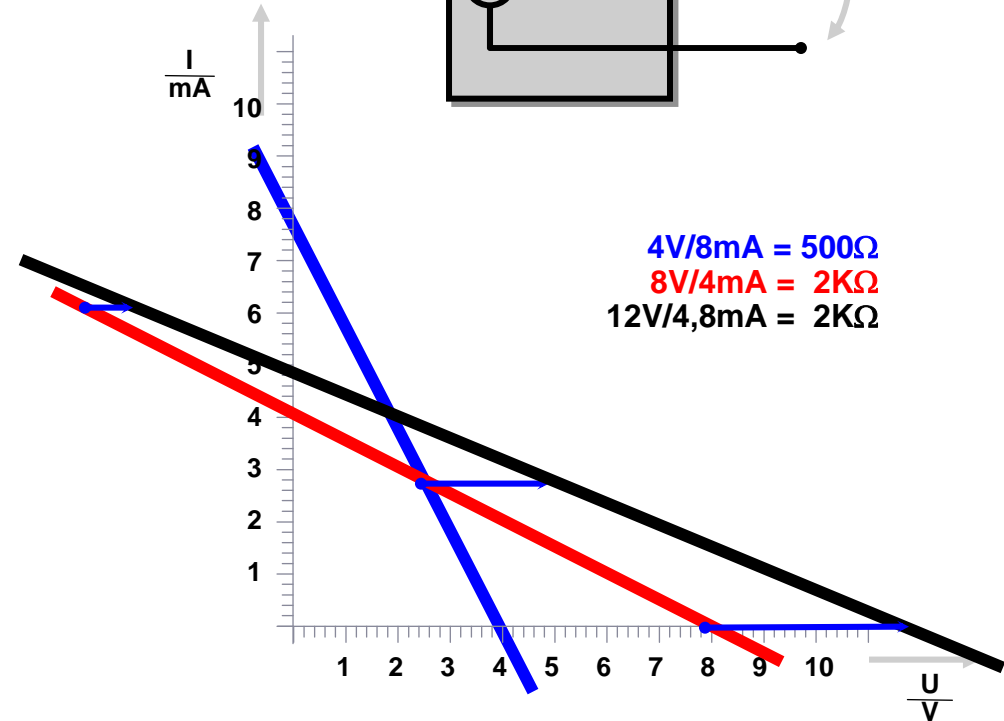
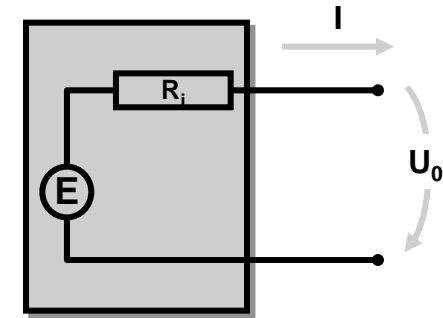
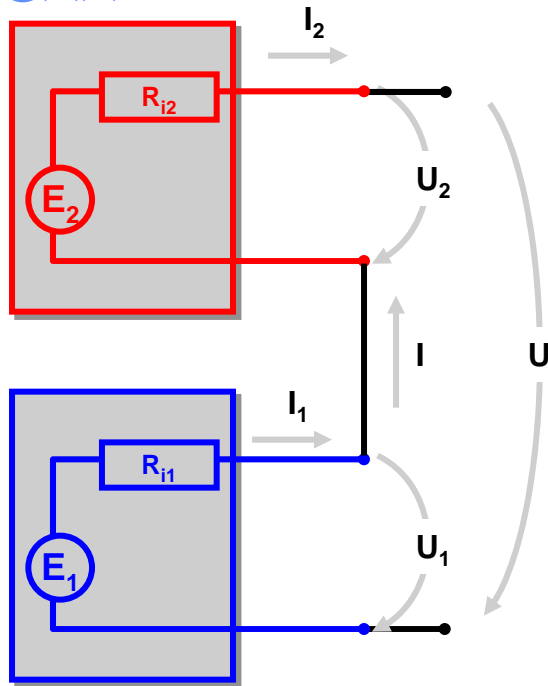


Ein Zweipol wird durch die „ideale“ Ursprungung E und den Innenwiderstand R_i beschrieben!



Reihenschaltung von Zweipolen

Digitale Systeme



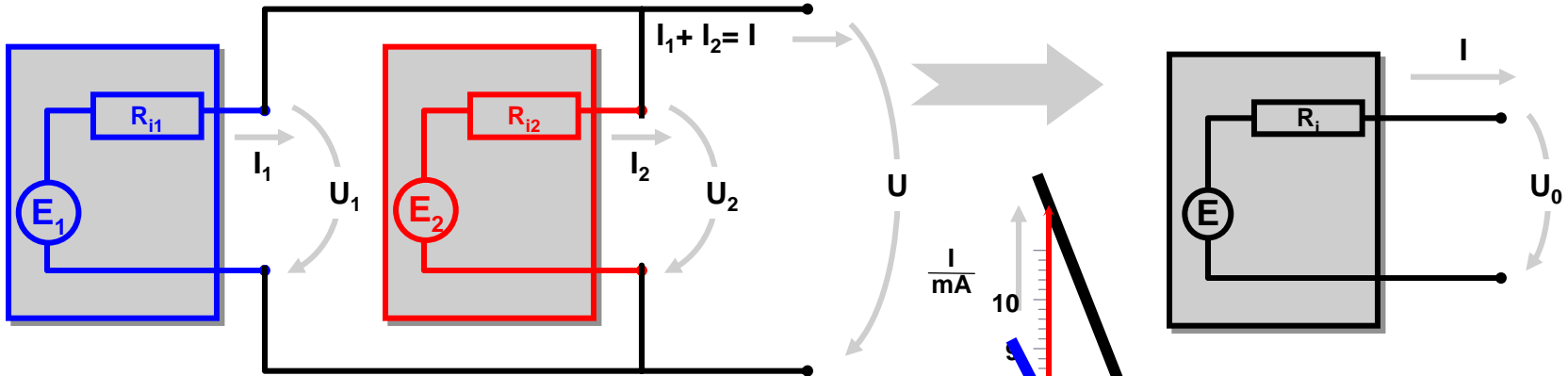
Berechnung

$$I = I_1 = I_2$$

$$U = U_1 + U_2$$

$$R_i = R_{i1} + R_{i2}$$

Man addiert die Spannungen bei gleichem Strom!



Berechnung

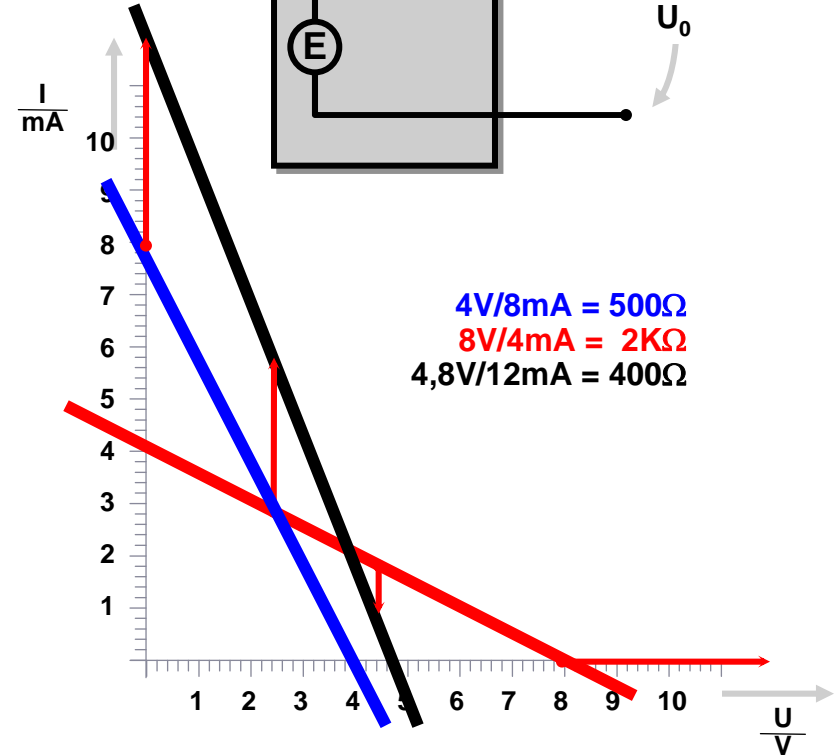
$$I = I_1 + I_2$$

$$U = U_1 = U_2$$

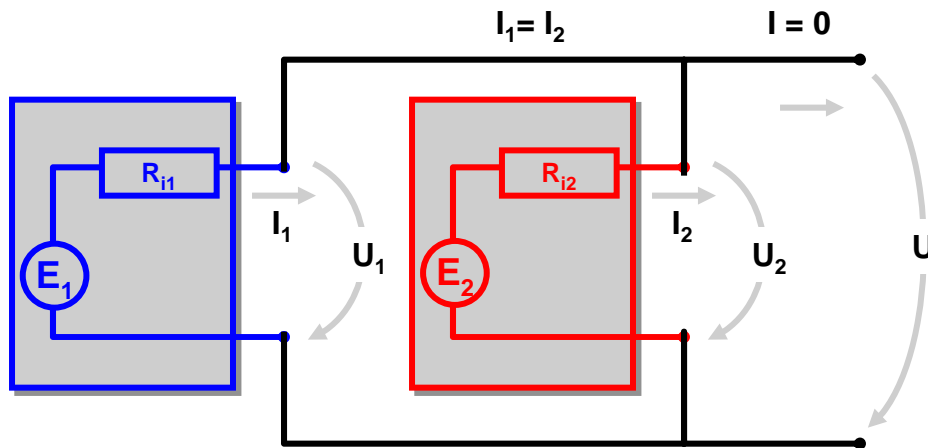
$$R = R_{i1} \parallel R_{i2}$$

$$= \frac{R_{i1} * R_{i2}}{R_{i1} + R_{i2}}$$

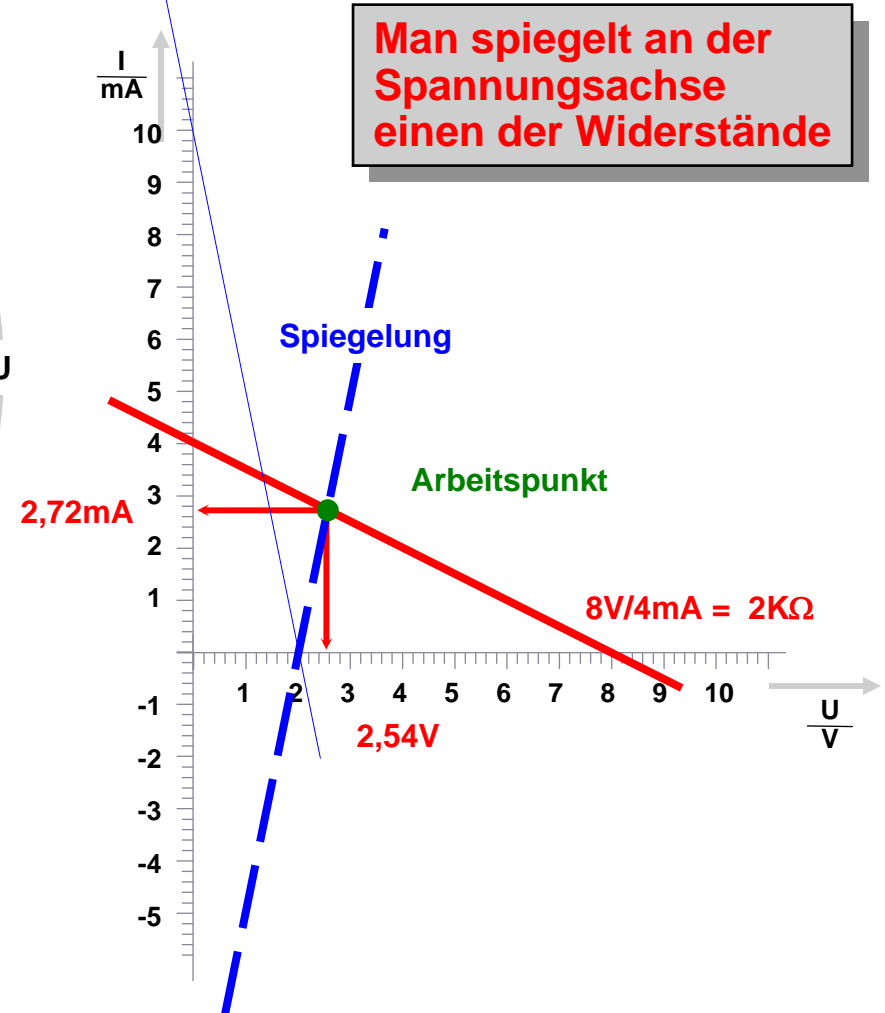
$$E = E_2 + \frac{(E_1 - E_2) * R_{i2}}{R_{i1} + R_{i2}}$$



Man addiert die Ströme bei gleicher Spannung!

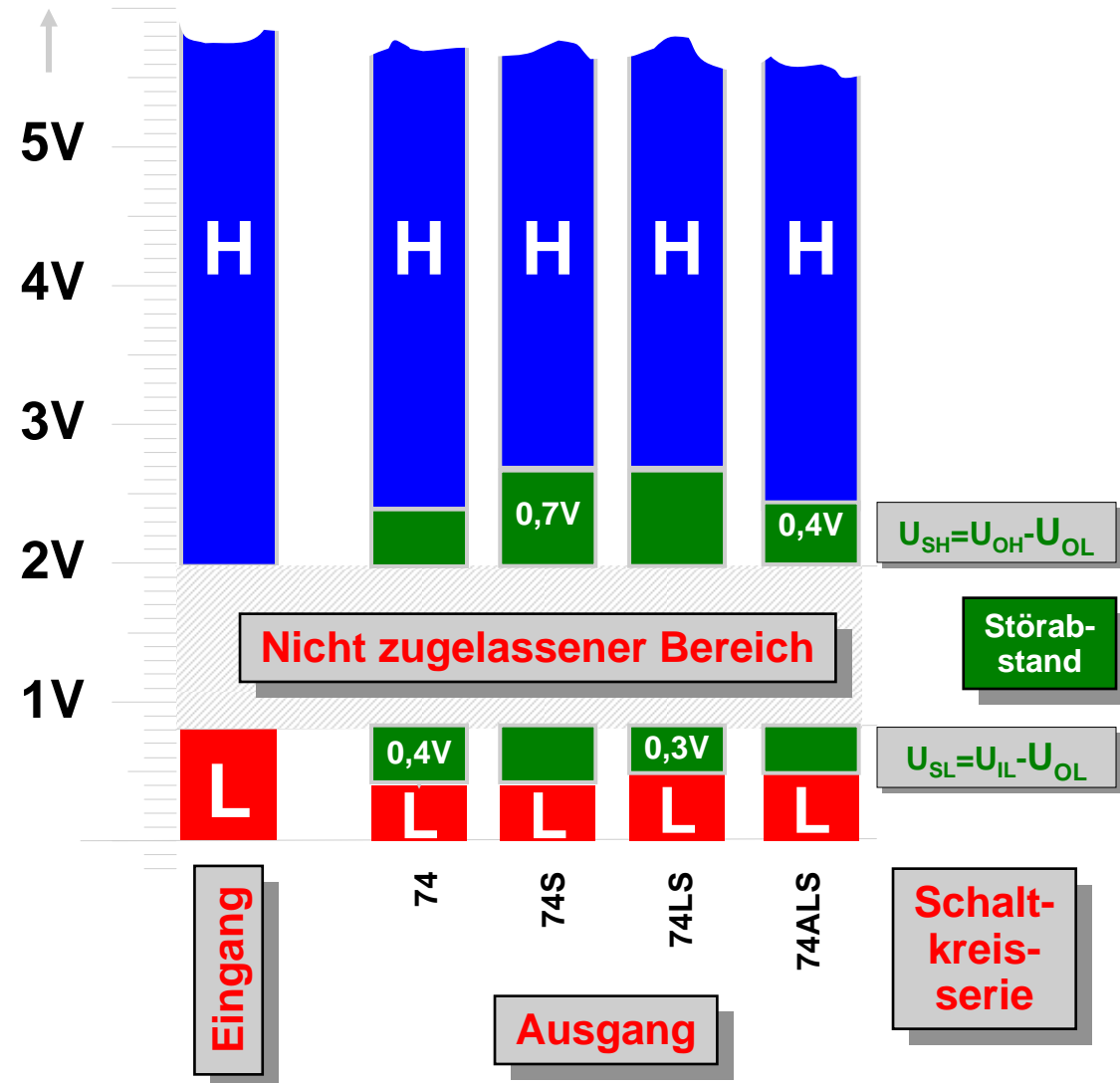
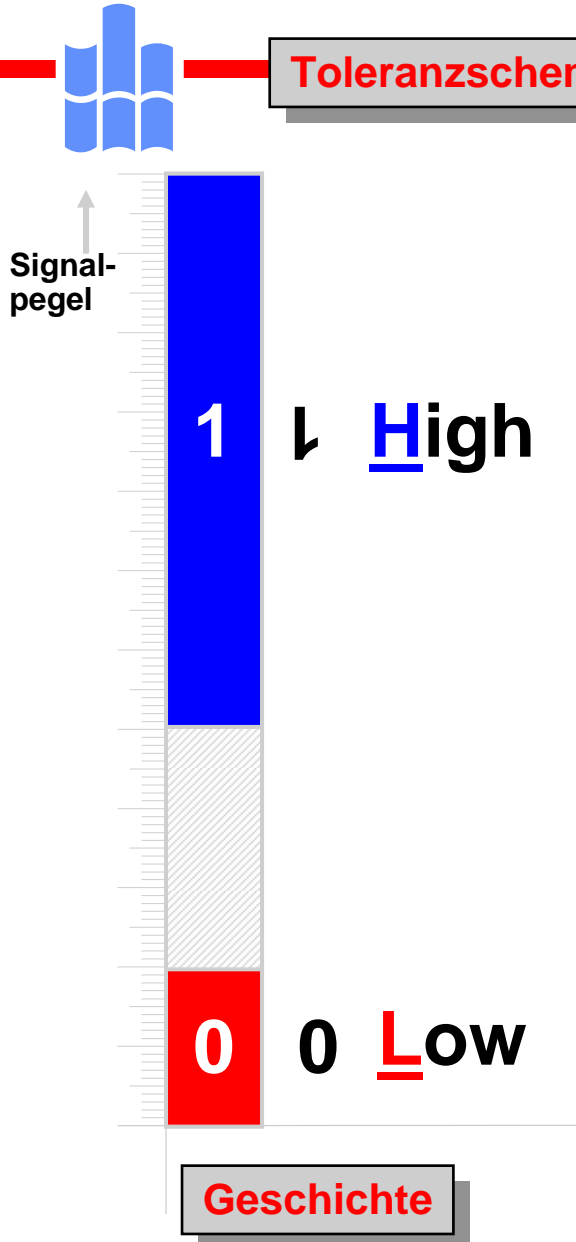


$$2\text{V}/10\text{mA} = 200\Omega$$



Toleranzschemen / Störabstände

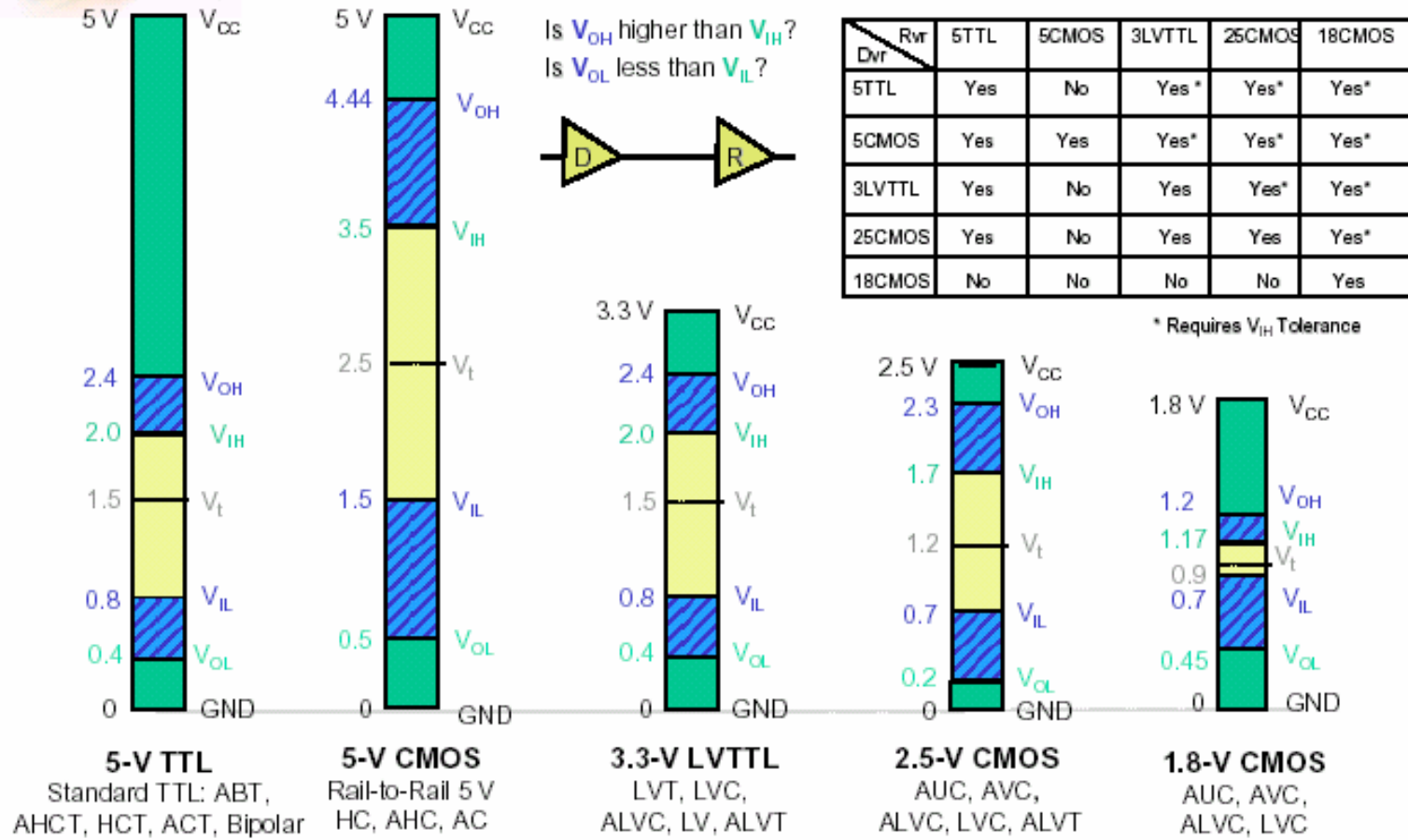
Digitale Systeme





IC Basics

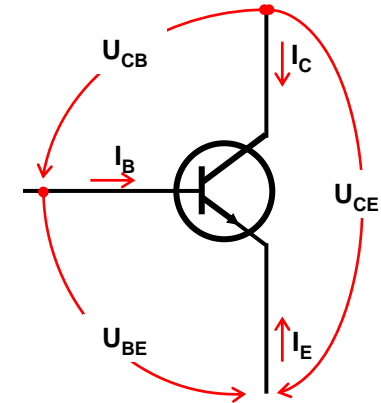
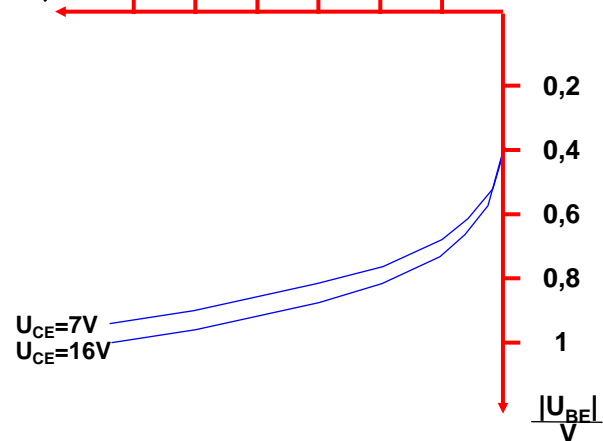
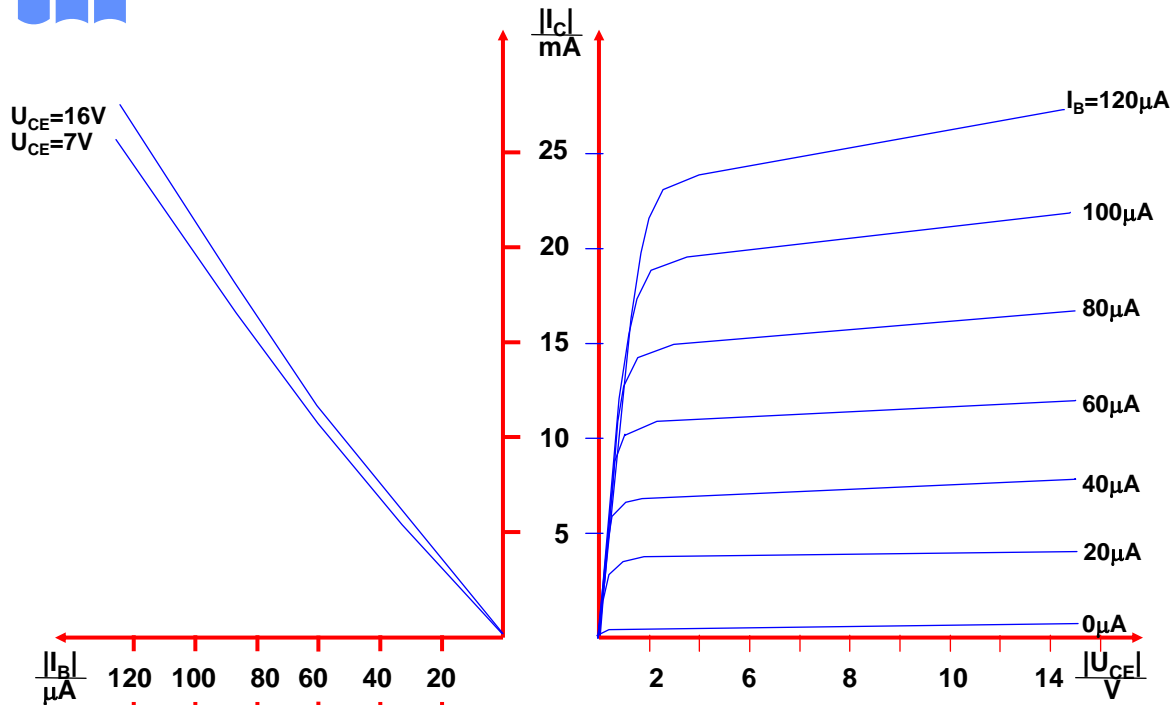
Comparison of Switching Standards





Kennlinienfelder eines npn - Transistors

Digitale Systeme

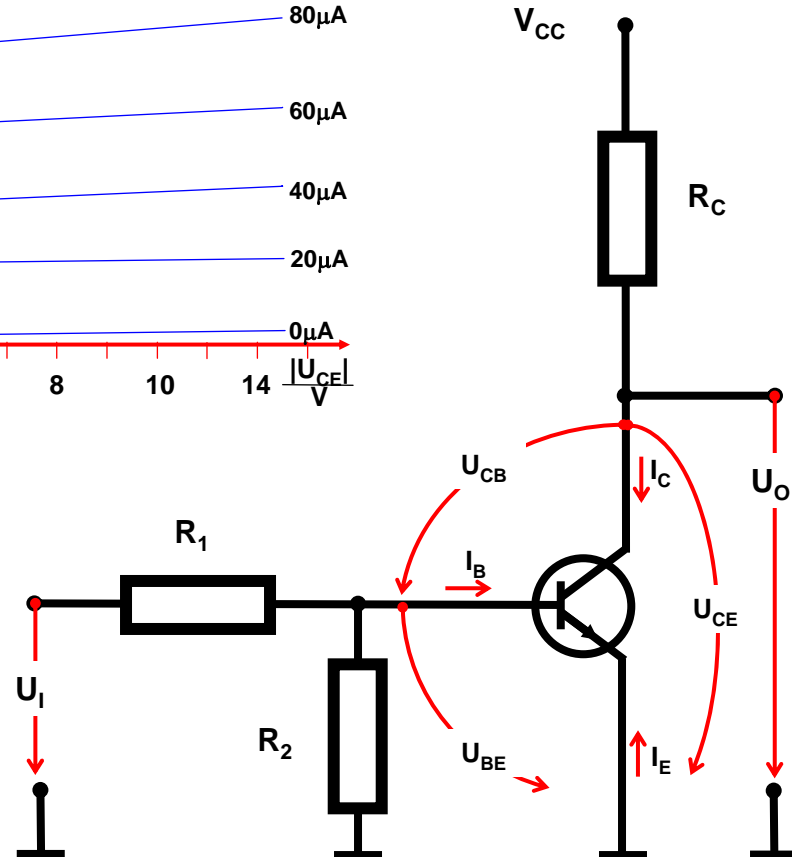
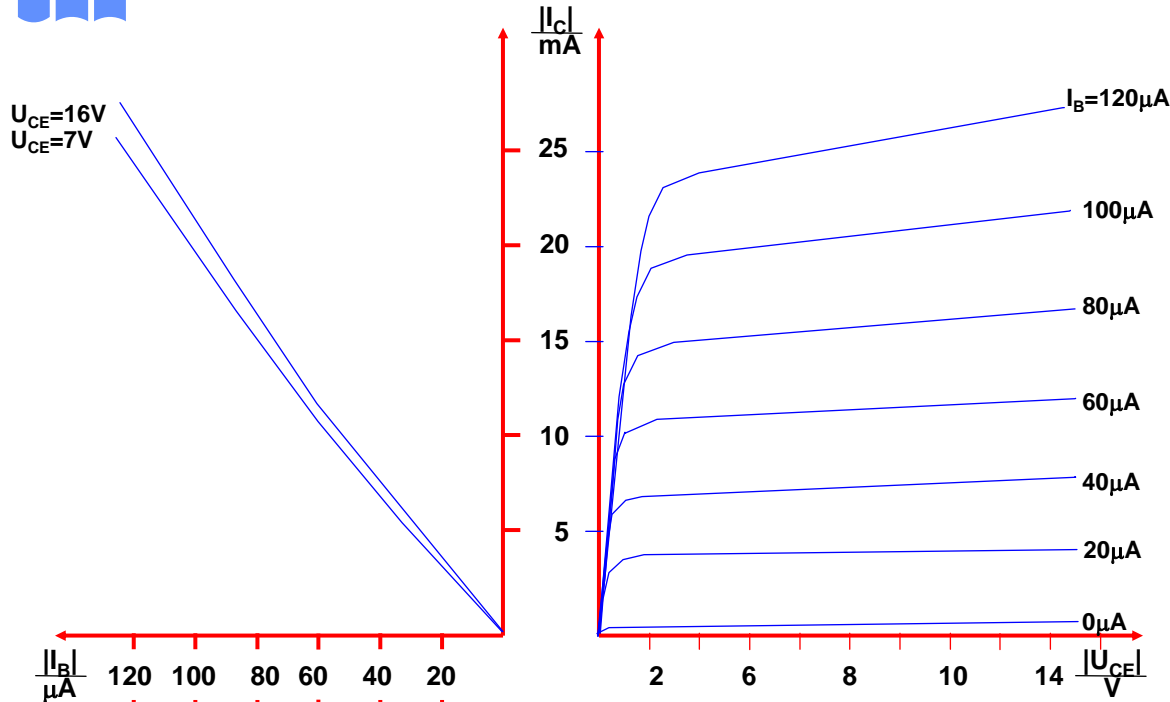


Transistorgleichungen

$$I_C + I_B + I_E = 0$$

$$U_{CE} = U_{CB} + U_{BE}$$

$$I_C / I_B = B_N$$



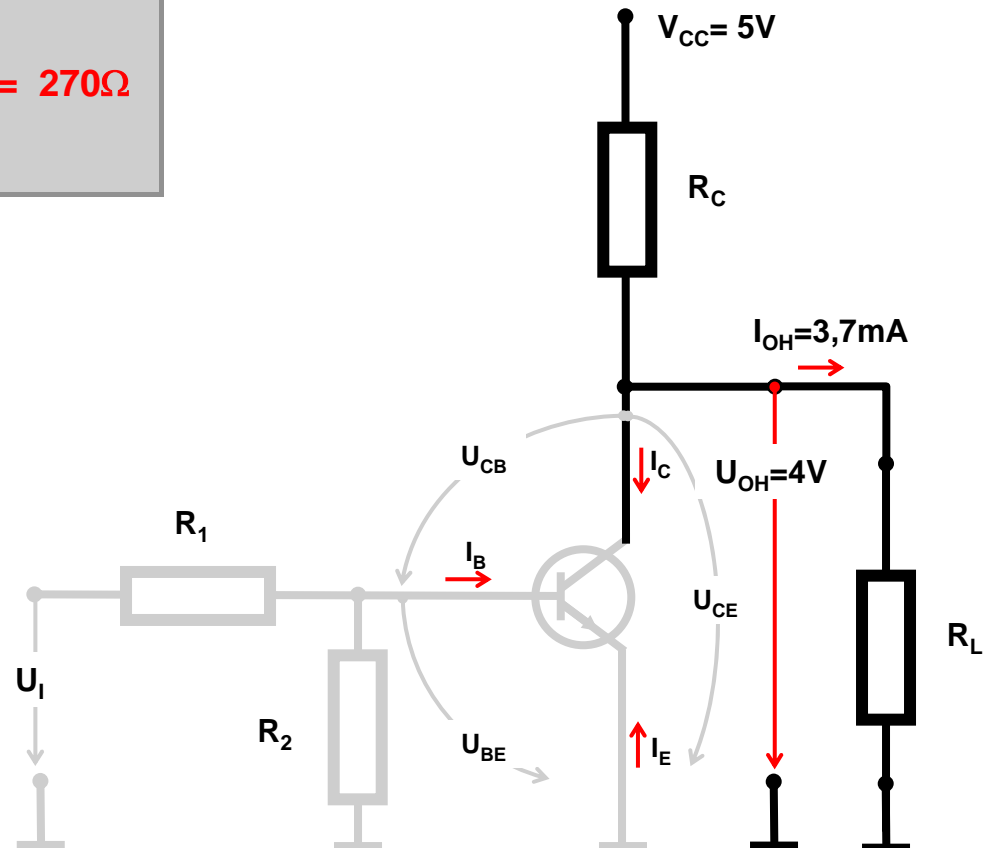
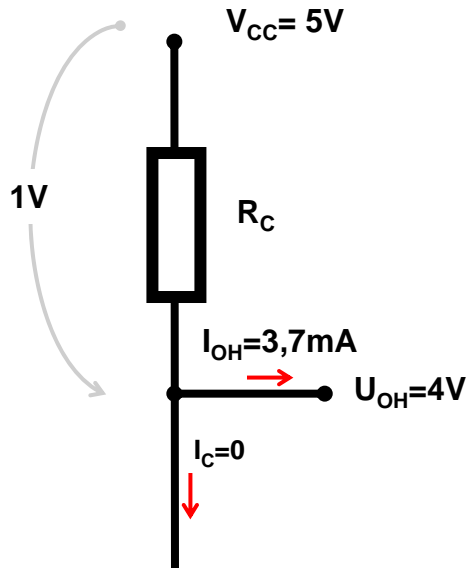


1

Berechnung R_C

$V_{CC} = 5V$
 $U_{OH} = 4V$
 $I_{OH} = 3,7mA$

$$R_C = \frac{1V}{3.7mA} = 270\Omega$$

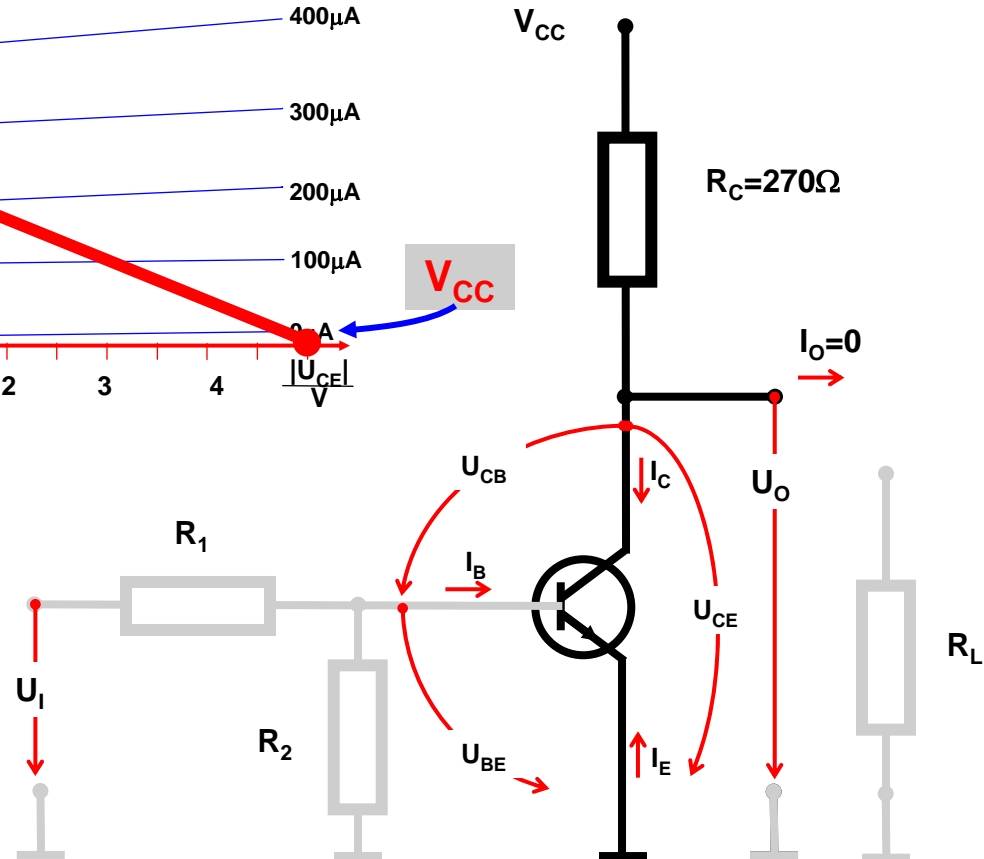
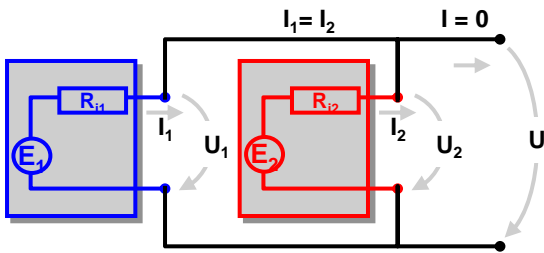
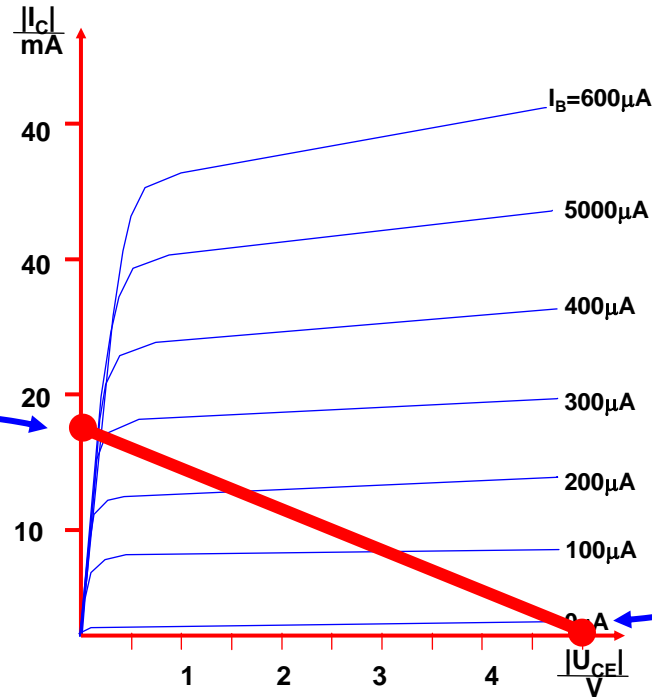




2

Einzeichnen der Arbeitsgeraden

$$i_C = \frac{5V}{270\Omega} = 18,5mA$$



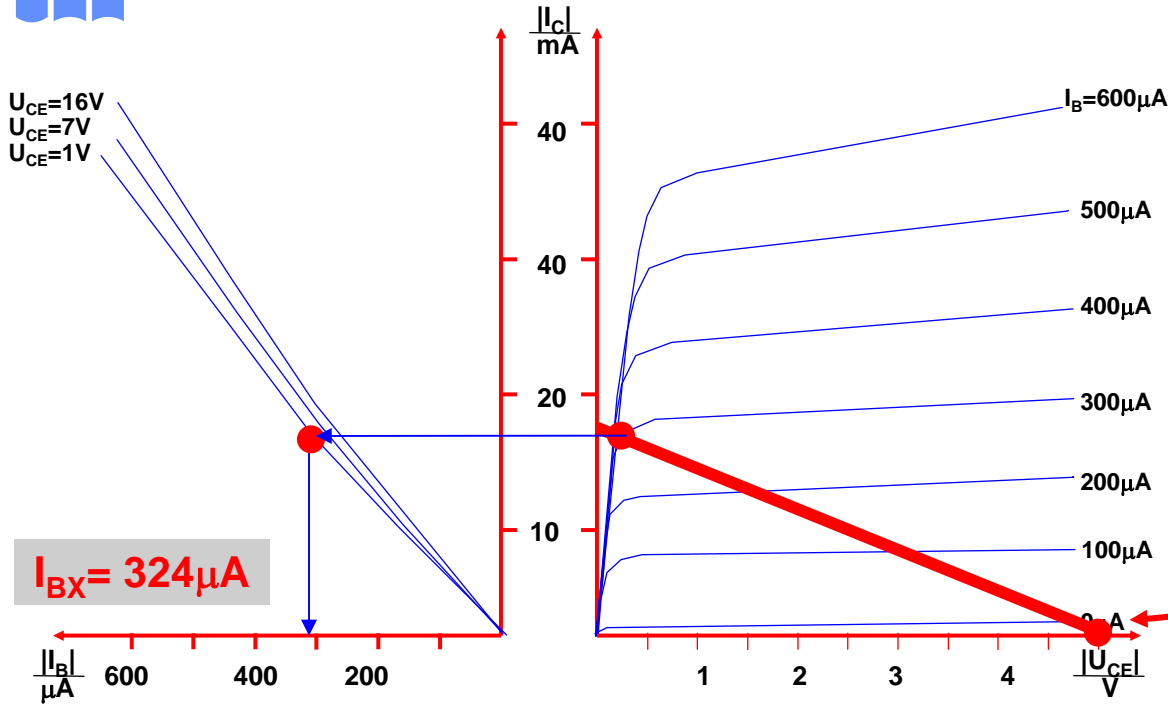


Ermittlung des Basisstromes

Digitale Systeme

3

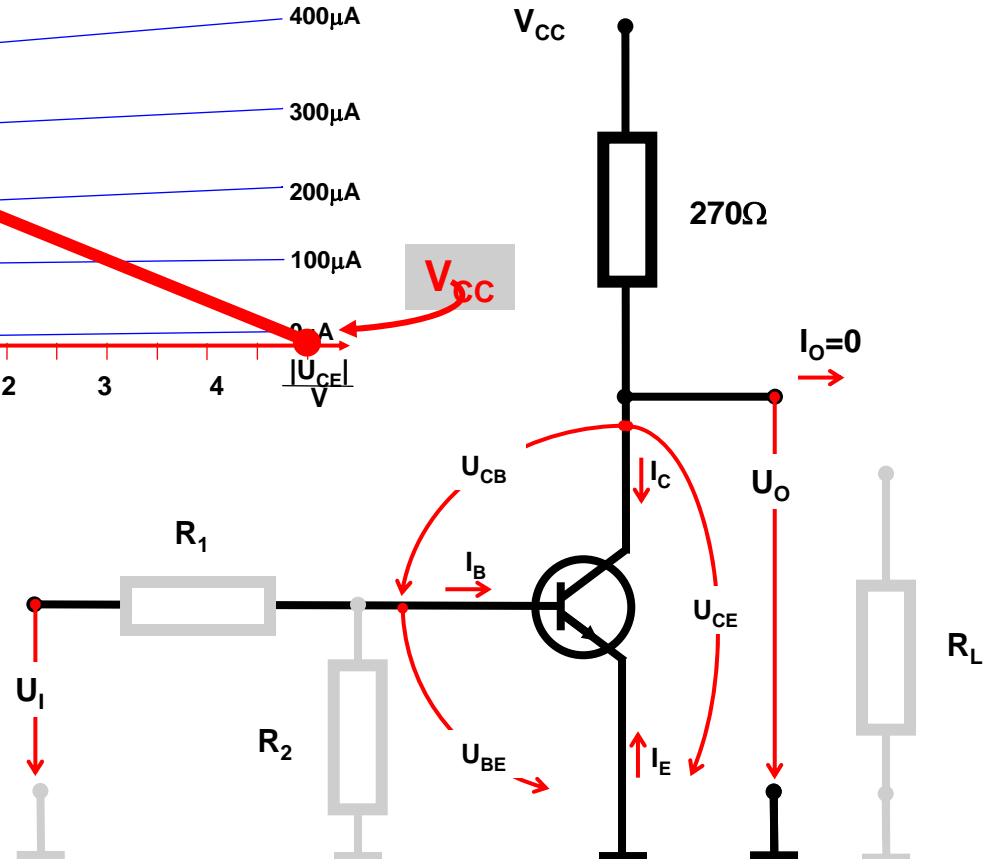
Ermittlung des Basisstroms



$I_{Bx} = 324 \mu A$

$$I_{Bx} = \frac{I_{Cx}}{B_N}$$

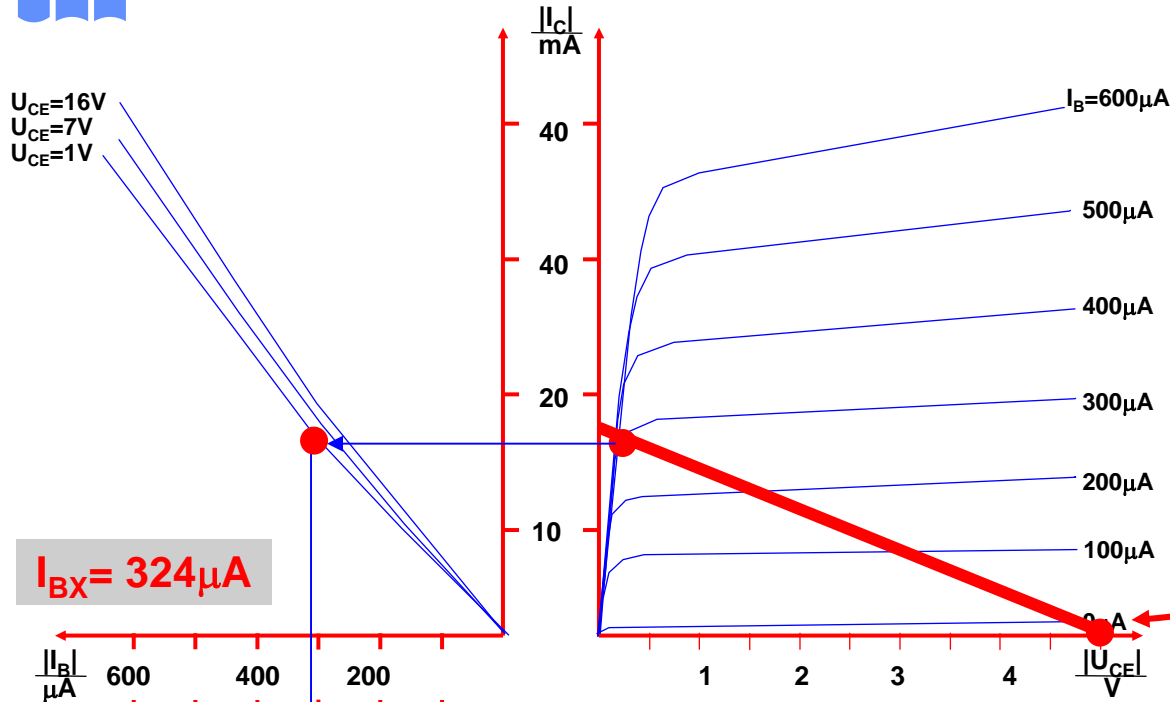
$B_N = \text{Gro\ss} \text{signalstromverst\u00e4rkung}$



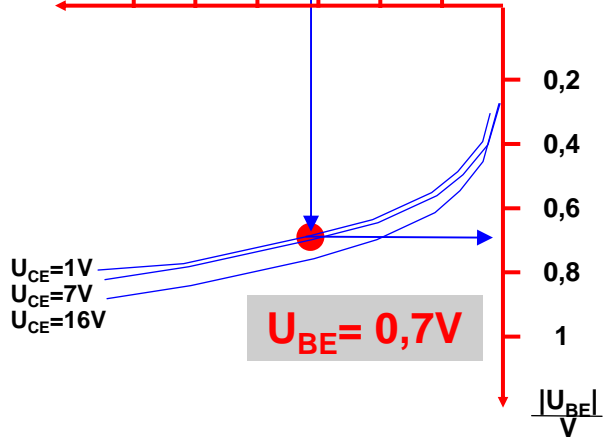


4

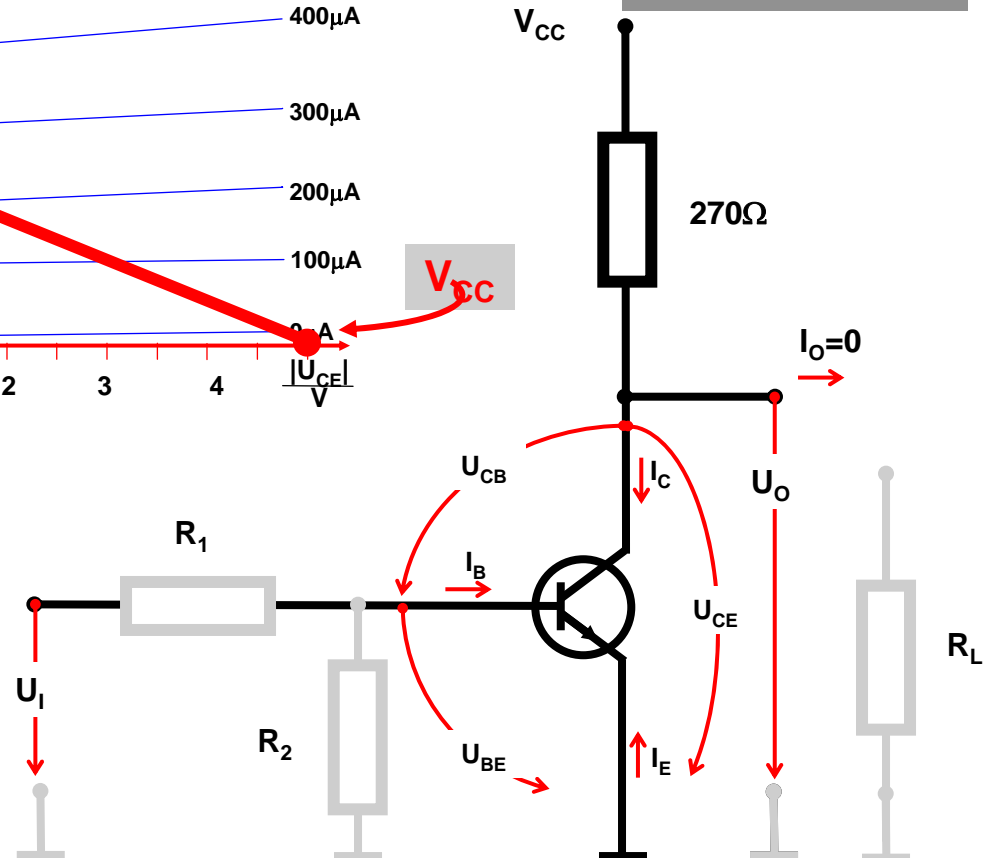
Ermittlung der Basis-Emitterspannung U_{BE}



$I_{BX} = 324 \mu A$



$U_{BE} = 0,7V$





5

Zur Verbesserung des Störabstandes und der dynamischen Eigenschaften werden die Transistoren „über-und untersteuert“ !

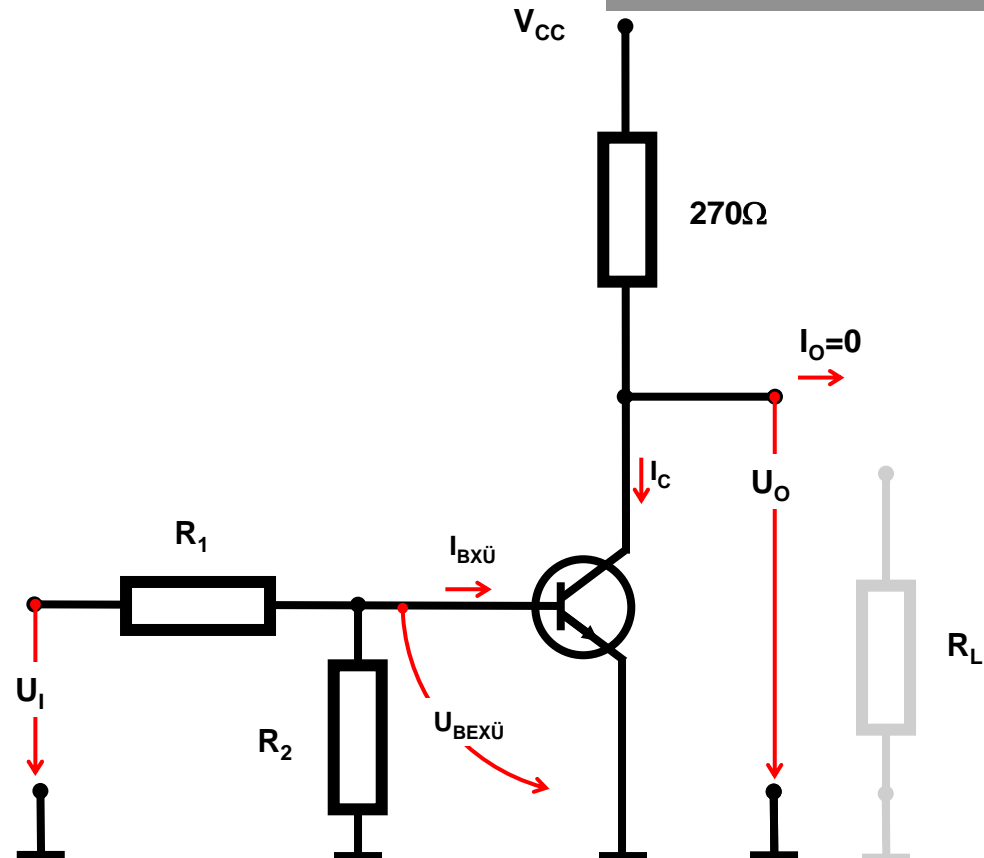
m --> Übersteuerungsfaktor
n --> Stromteilstfaktor

$$I_{BX\ddot{u}} = m * I_{BX}$$

$$R_1 = \frac{U_{IH} - U_{BEX}}{(n+1) * I_{BX\ddot{u}}}$$

$$R_2 = \frac{U_{BEX}}{n * I_{BX\ddot{u}}}$$

Dimensionierung
des Basis-
spannungsteilers





U_{IH} --> min. "H" am Eingang = 3V
m --> Übersteuerungsfaktor = 5
n --> Stromteilkfaktor = 0,5

$$I_{BXÜ} = 5 * 324\mu A = 1,62mA$$

$$R_1 = \frac{U_{IH} - U_{BEXÜ}}{(n+1) * I_{BXÜ}} = \frac{3V - 0,7V}{(0,5+1) * 1,62mA} = 946 \Omega$$

$$R_2 = \frac{U_{BEXÜ}}{n * I_{BXÜ}} = \frac{0,7V}{0,5 * 1,62mA} = 820 \Omega$$

Dimensionierung
des Basis-
spannungsteilers

